



*Measuring and mOdelling
traffic COngestion and POLLution*

MOCOPo: status of data collection tasks in January 2012

January 2012
MOCOPo team

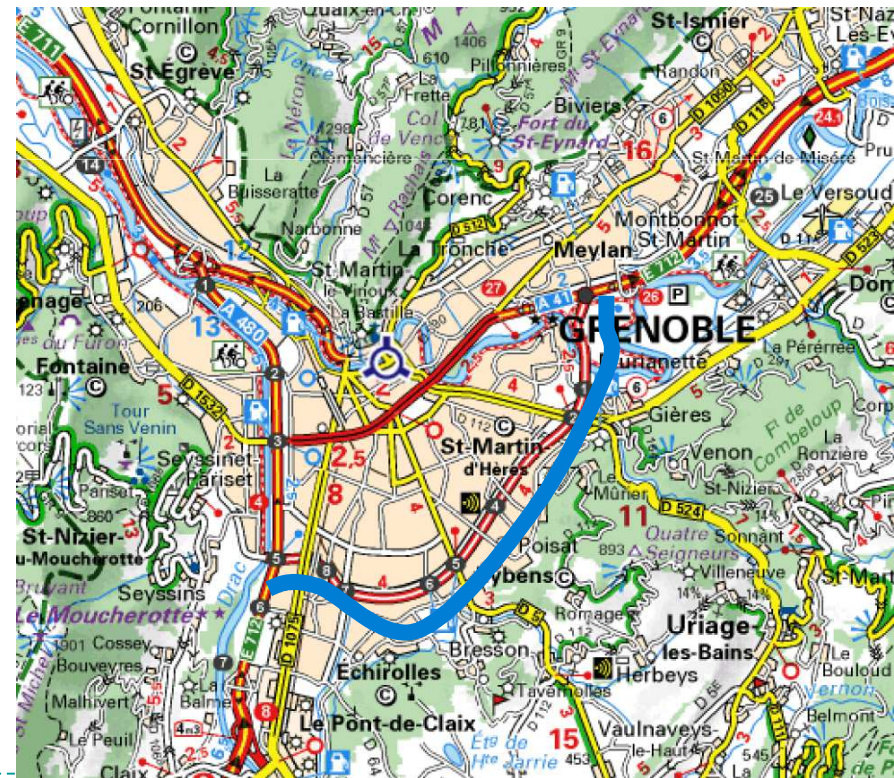
MOCOPo: Some facts

- ▶ A project funded by the French Ministry of Transportation (350 k€)
 - ▶ Dates:
 - ▶ Beginning: January 2011 End: December 2013
 - ▶ First year: Measurements Second and third years: Modeling enhancements
 - ▶ 6 partners
 - ▶ IFSTTAR (Lyon, Paris, Nantes),
 - ▶ INRIA (Grenoble),
 - ▶ French Ministry of Transportation (Grenoble, Lyon, Angers)
 - ▶ Association of Pollution Measurement ASCOPARG (Grenoble),
 - ▶ CEREAS (Paris)
 - ▶ ENTPE
- and more than 30 individuals
- ▶ A joint data collection project: PM-Drive devoted only to high precision pollution measurements led by Aurélie Charron (LTE-IFSTTAR) with the involvement of additional partners: LGGE (Grenoble), LCP (Marseille), LCM (Chambery)

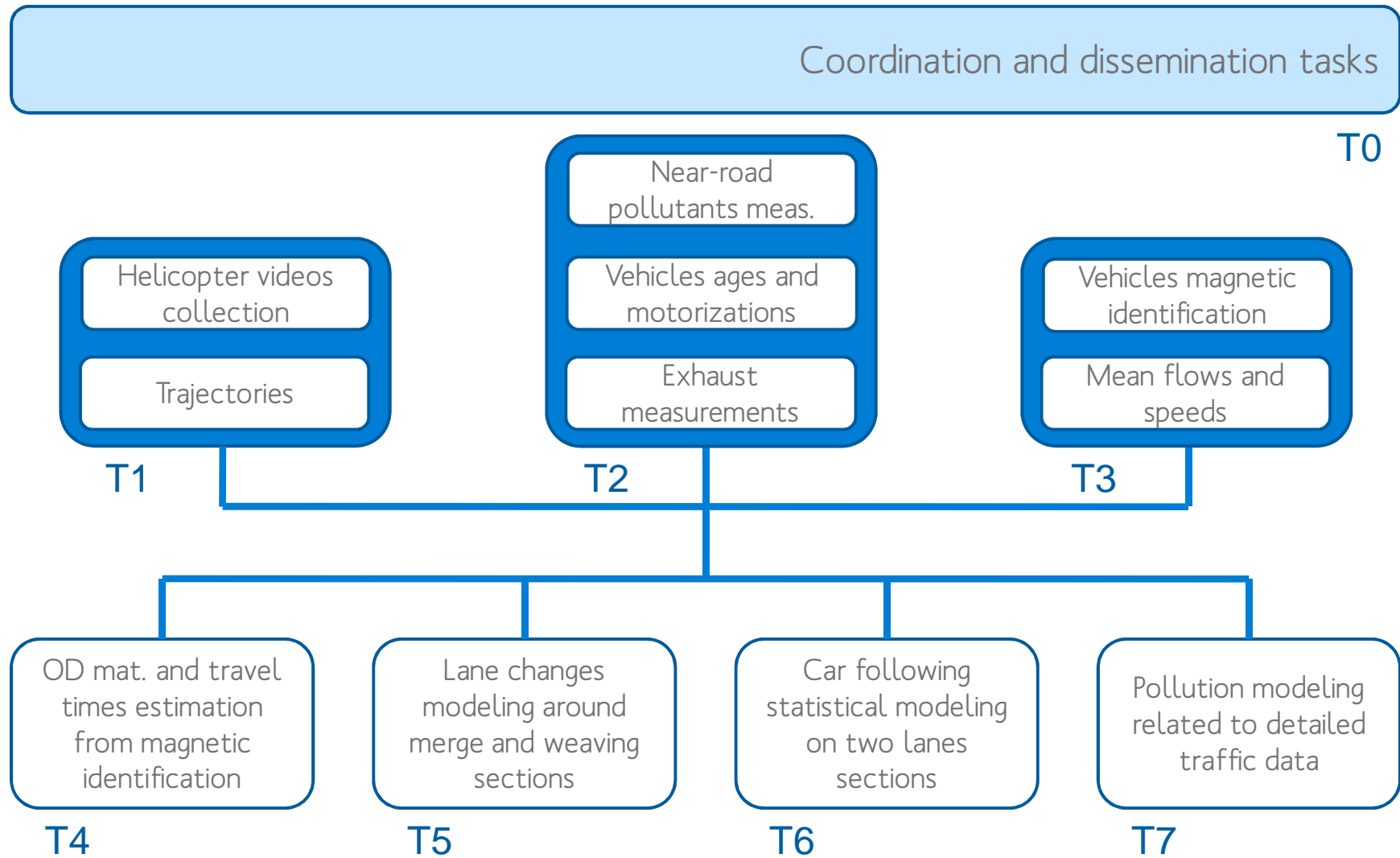


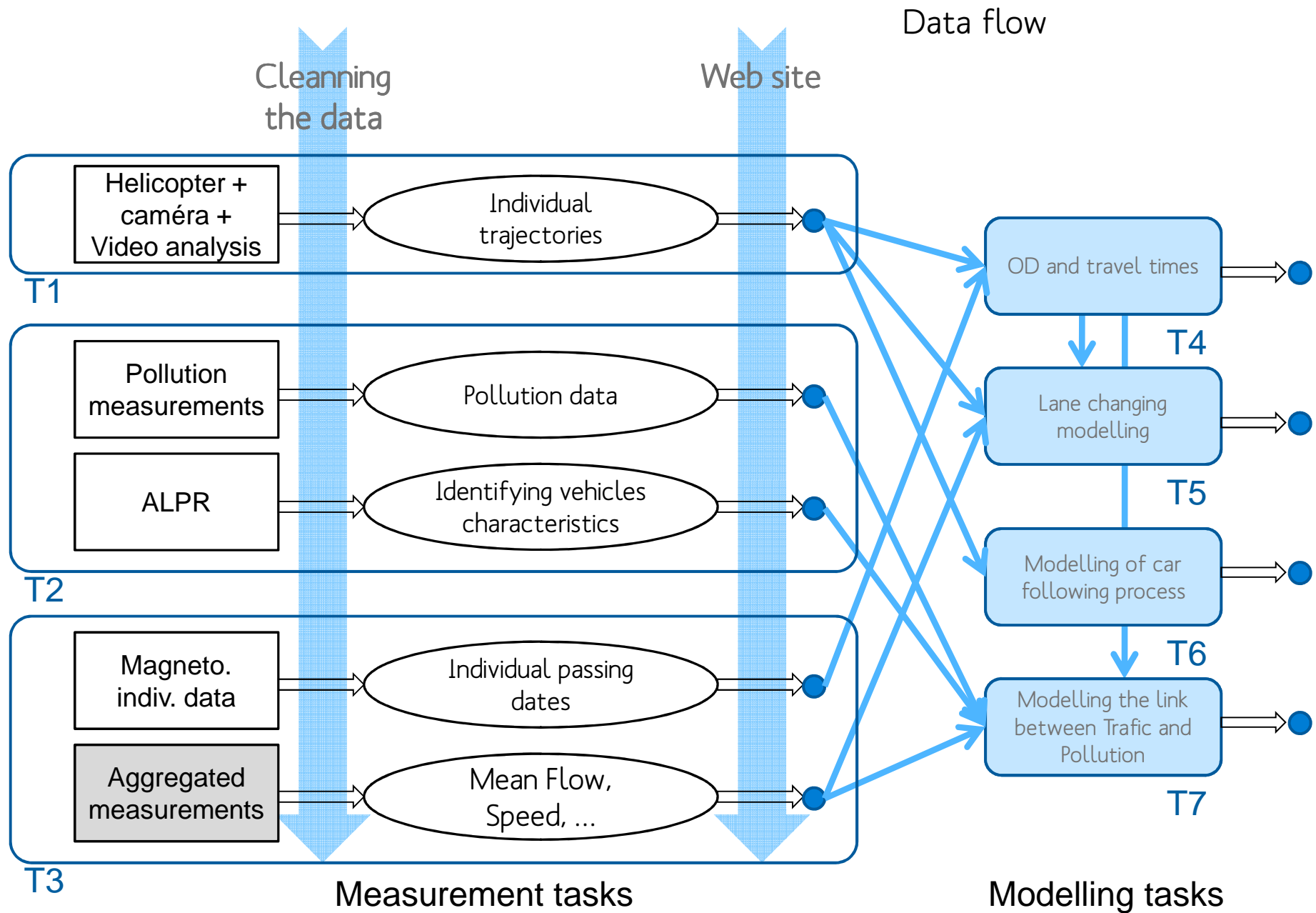
MOCaPo: global objectives

- ▶ Collect data on a simple and congested highway
 - ▶ The RN87 in South of Grenoble about 10 km long;
 - ▶ A 2x2 lanes highway
 - ▶ Simultaneously collect
 - ▶ Trajectories
 - ▶ Pollutants
 - ▶ On-road traffic data
 - ▶ Thus, allowing better modeling



Global organization





Task 1: trajectories data collection



5 days and 3 zones of helicopter fights

*Zone 1: Meylan
merge (from left to
right)*



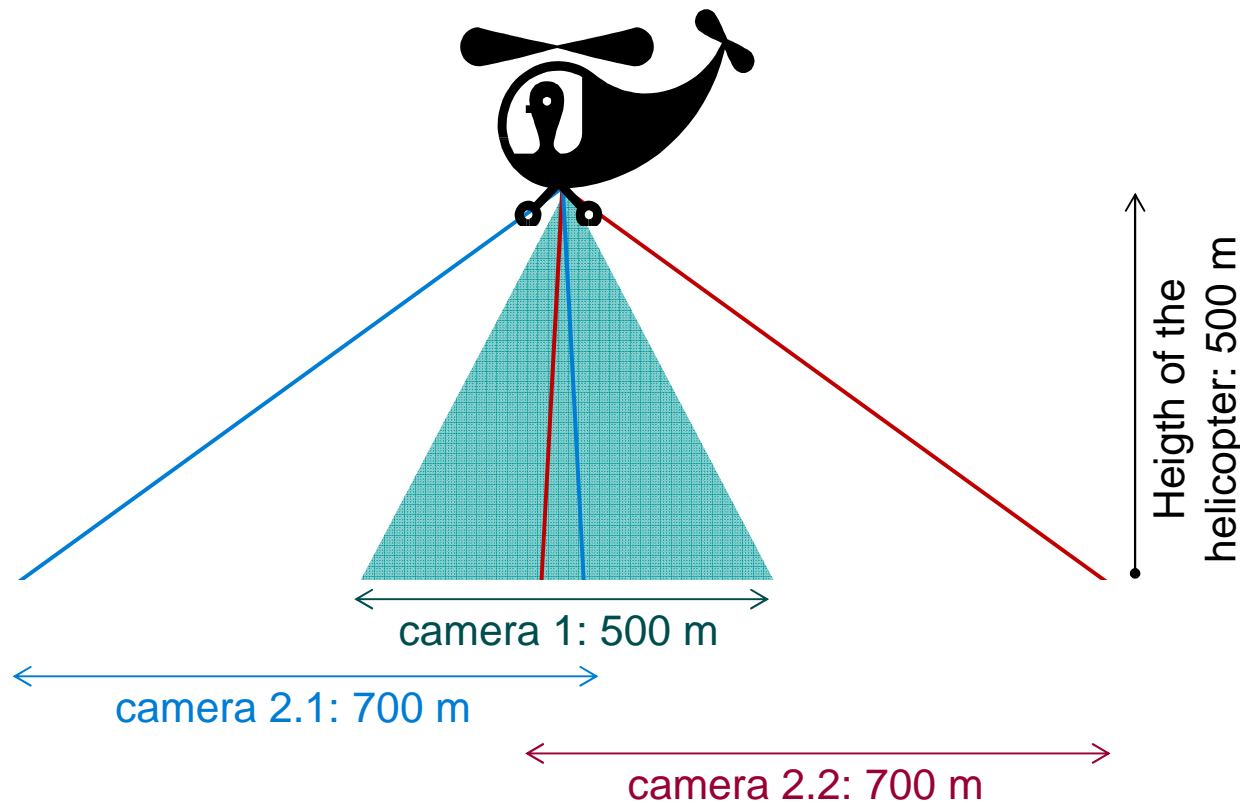
Zone 2: Eybens



*Zone 3:
Le Rondeau*



Three cameras for a complete measurement



- ▶ Camera 1
 - ▶ 2500*1000 pixels
 - ▶ More than 20 images/second
- ▶ Cameras 2.1 and 2.2
 - ▶ To determine upstream and downstream flows



Summary: 7 h 10 of potentially perfect data
and 8 h 40 of analyzable data

	Zone 1 - merge 1h50 (2h40)		Zone 2 - standard section 1h30 (2h10)		Zone 3 - weaving section 3h50 (3h50)	
	duration	Remark/period	duration	Remark/period	duration	Remark/period
Mon. 12	15'	8:16 - 8:32			50'	16:12 - 17:02
Tues. 13	51'	No image of camera 2.1 downstream 7:29 - 8:21	40'	No image of camera 2.1 downstream 8:40 - 9:20		
Wed. 14	45'	Many clouds and rain; helicopter at 450 m	15'	9:26 - 9:41	60'	16:21 - 17:21
Thurs. 15	35'	7:32 - 8:06	50'	8:54 - 9:44	60'	16:17 - 17:17
Fri. 16	60'	7:58 - 8:58	25'	9:04 - 9:28	60'	16:07-17:07

In global, more than 20,000 vehicles
will be precisely observed along 500 m



Video analysis

Digitalization made with the help of a software developed by TU Delft

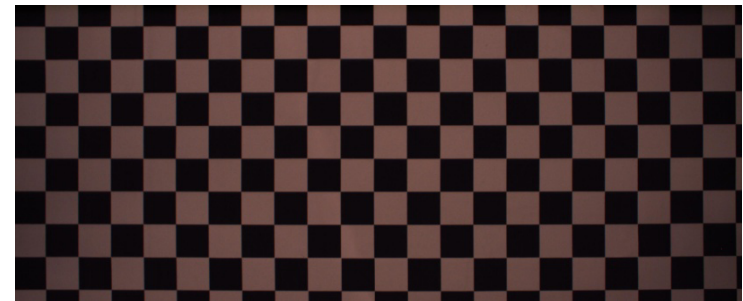
3 steps

- ▶ Stabilization
- ▶ Determination of the objects moving from one image to another
- ▶ Building up the vehicles trajectories from one image to another



First step: stabilization

- ▶ Image distortion correction
- ▶ Choose a reference image
- ▶ Define the region of interest



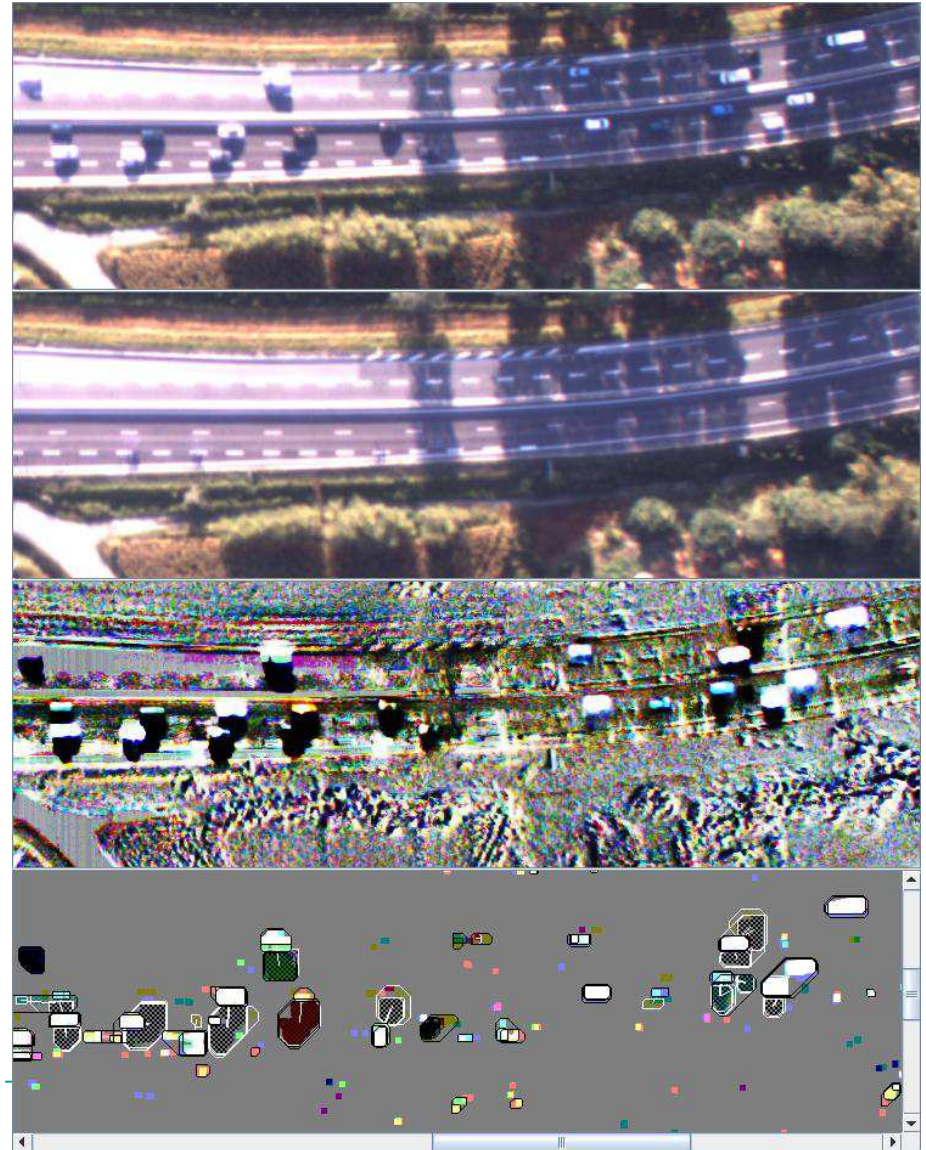
Step 2: identify what moves

Image from step 1

**“Nude”
image**

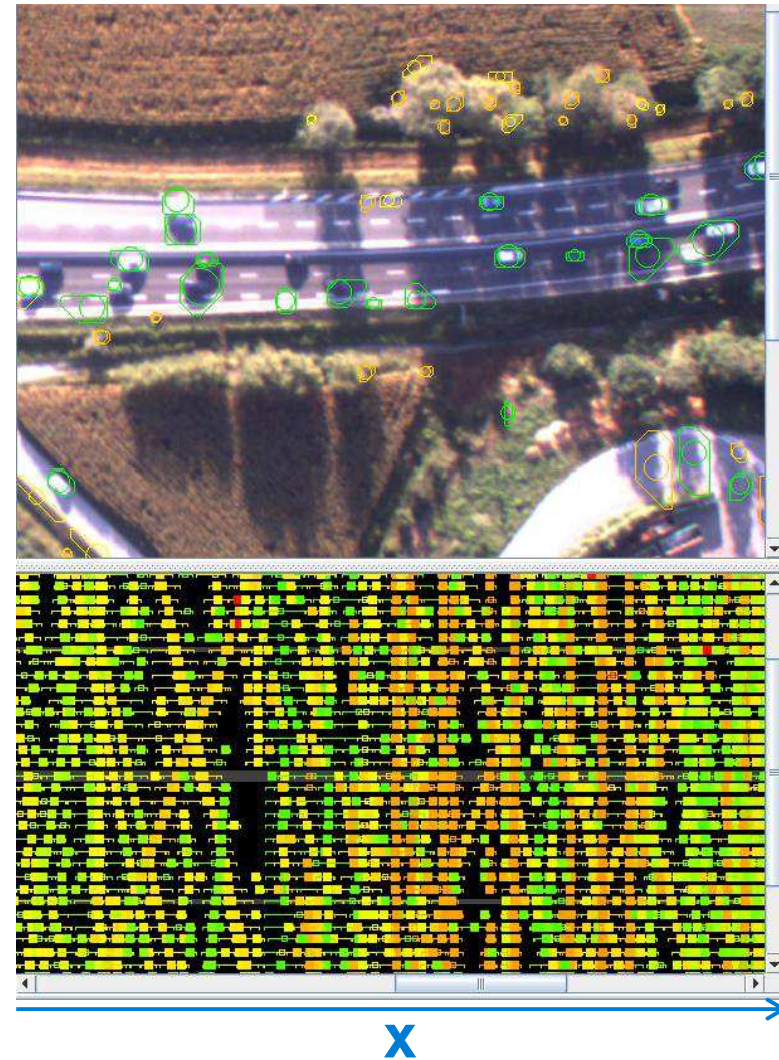
Difference

Moving spots



Step 3: building trajectories

- Connexion of the spots between two successive images



Task 2: Pollutants measurements



Three sub-tasks

- ▶ Complete and detailed data set was collected
 - ▶ 4 periods (winter, spring, summer, fall) of two weeks each;
 - ▶ 4 measurement locations
 - ▶ 3 near-road measurements
 - ▶ 1 urban background measurement
 - ▶ NO/ NO₂/ PM₁₀/ PM_{2.5}/ CO/ SO/ O₃
 - ▶ Weather data: wind speed, temperature
- ▶ Observation of the types (motorization, truck/car/...) and age of the vehicles for the period of spring
- ▶ Exhaust pipe measurements on three circuits made by a diesel light duty vehicle (NO_x, CO₂, CO and THC).



The data of the first sub task are available

- ▶ Also loop detector data for those periods

Trajectories data should be soon available

We hope you will use them!

<http://mocopo.ifsttar.fr>

